

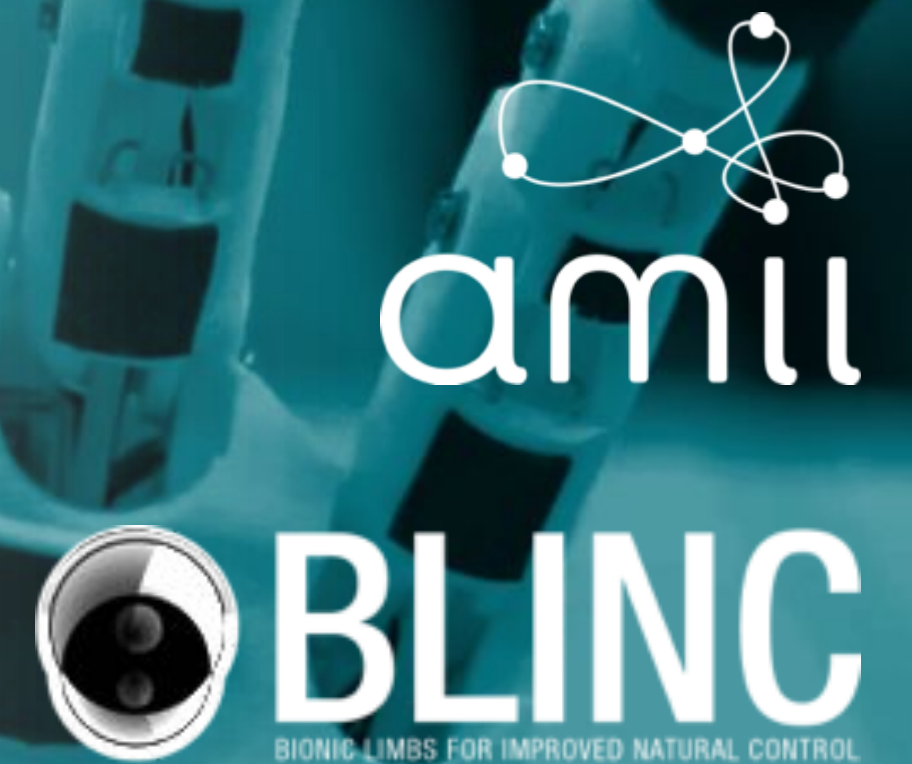
The Emerging Role of Machine-Learned Feedback in Neuroprostheses

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Fellow and Board of Directors, Alberta Machine Intelligence Institute (Amii)
Research Scientist and Edmonton Office Co-Lead, DeepMind*



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C.O.I. Disclosure

No affiliation (financial or otherwise) with pharmaceutical, medical device or medical communications organizations.

Other Industry Affiliations:

Senior Staff Research Scientist and Office Co-Lead, *DeepMind*

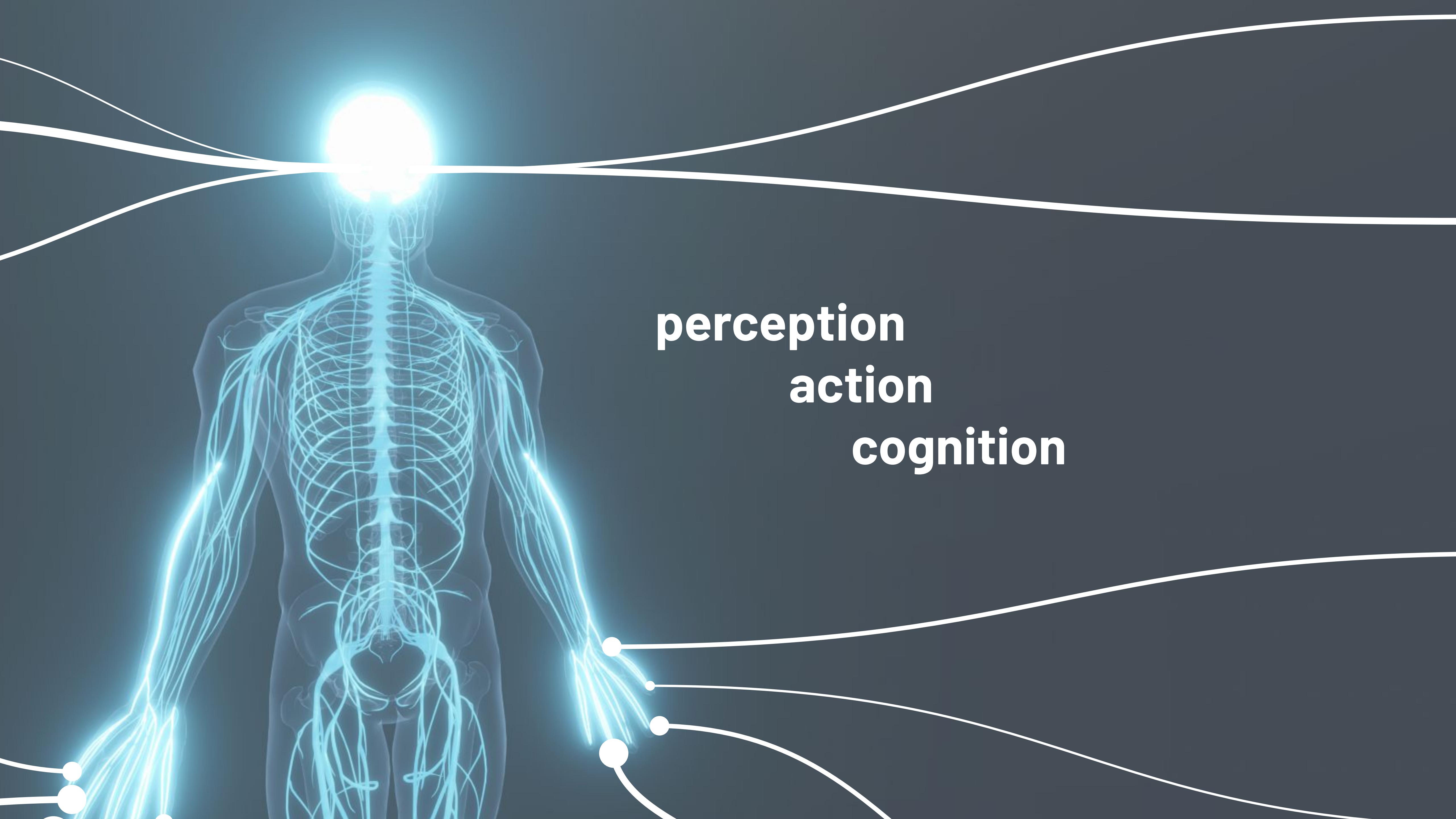
Board of Directors, *Alberta Machine Intelligence Institute*



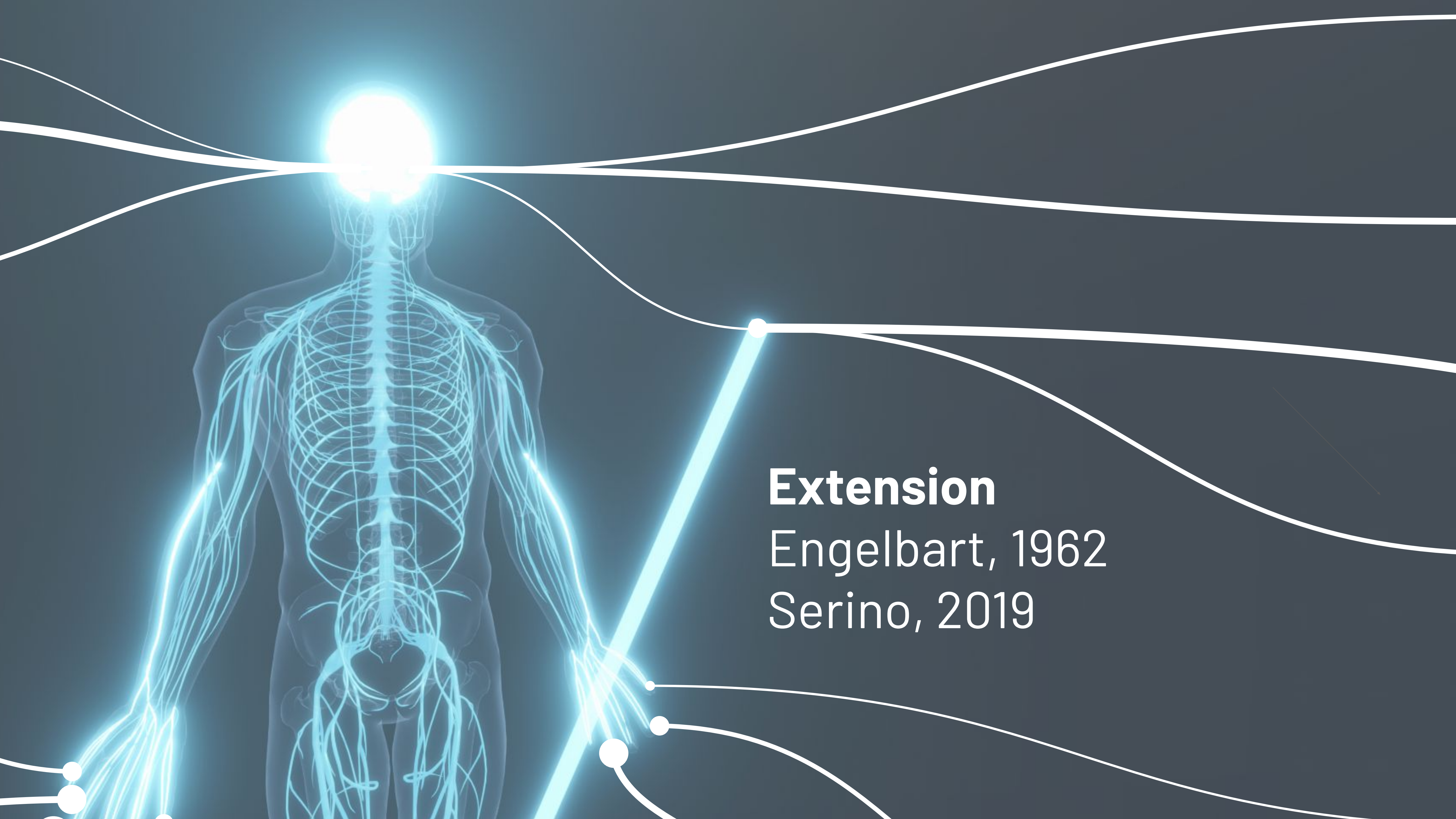


950BC - 700BC, The "Cairo Toe" (The University of Manchester),
<https://www.theatlantic.com/technology/archive/2013/11/the-perfect-3-000-year-old-toe-a-brief-history-of-prosthetic-limbs/281653/>
Nerlich, et al., *Lancet*, 356: 2176-79, 2000.

Video courtesy:
Amii / Chris Onciul



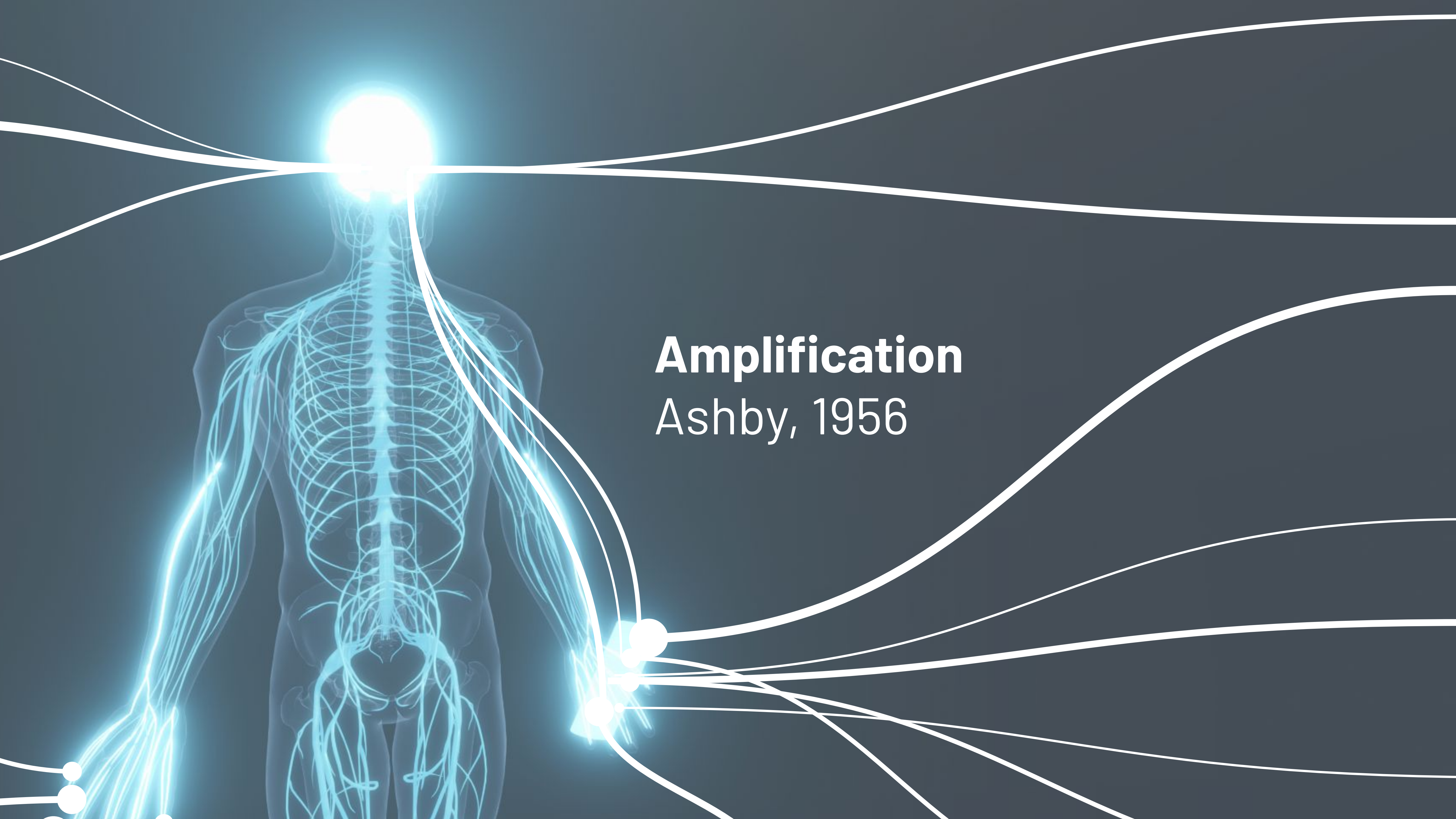
perception
action
cognition



Extension

Engelbart, 1962

Serino, 2019



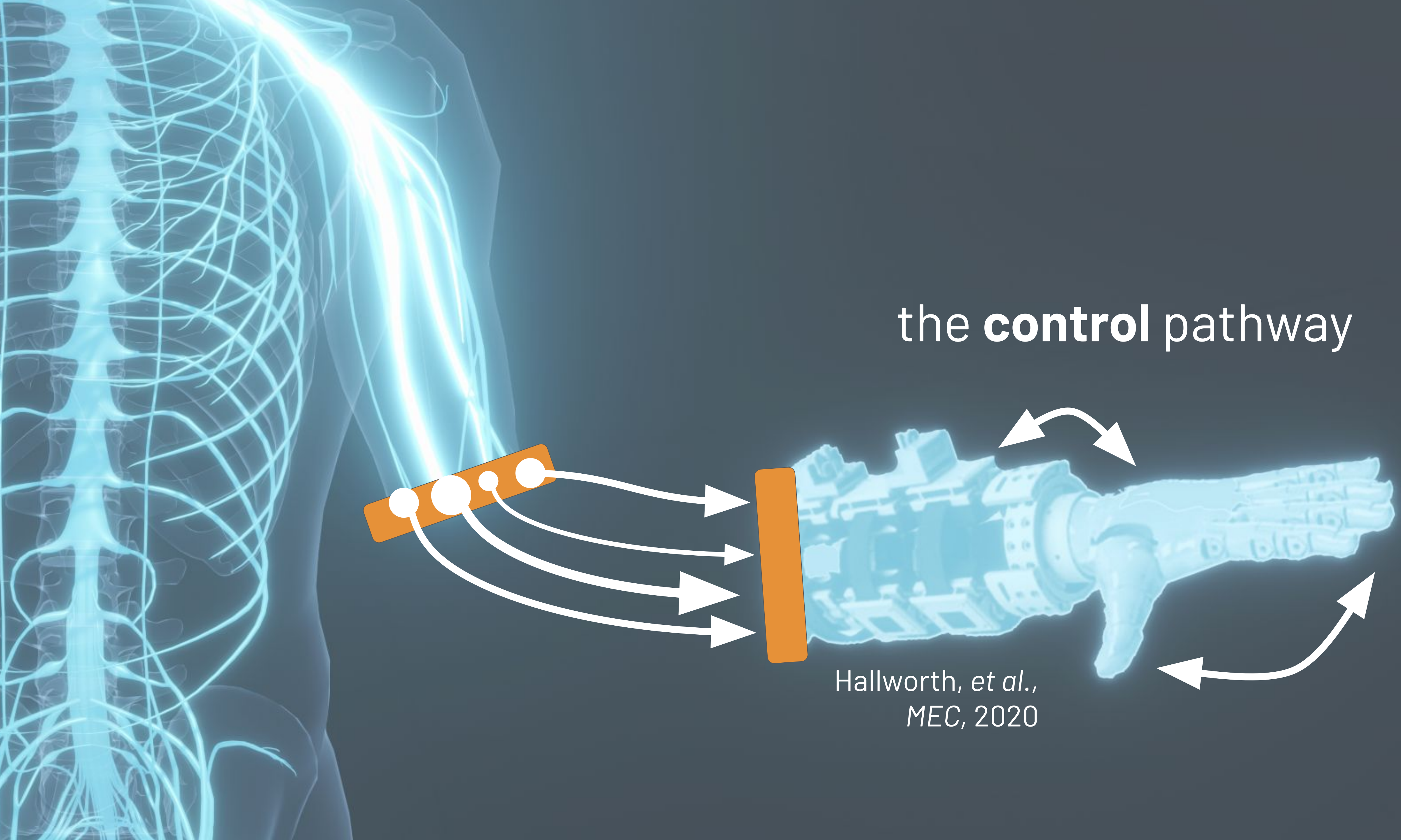
Amplification

Ashby, 1956



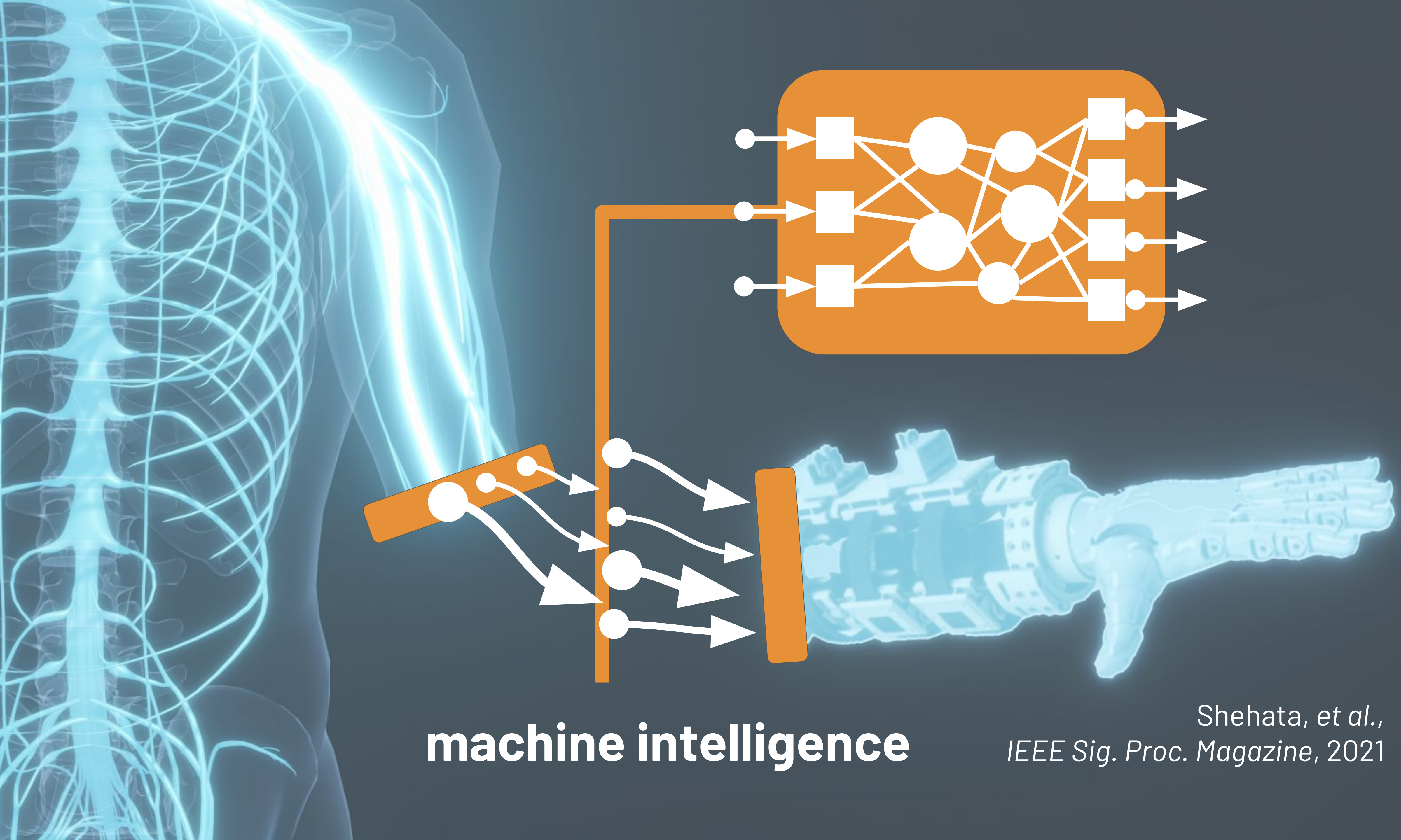
Tightly Coupled

Licklider, 1960



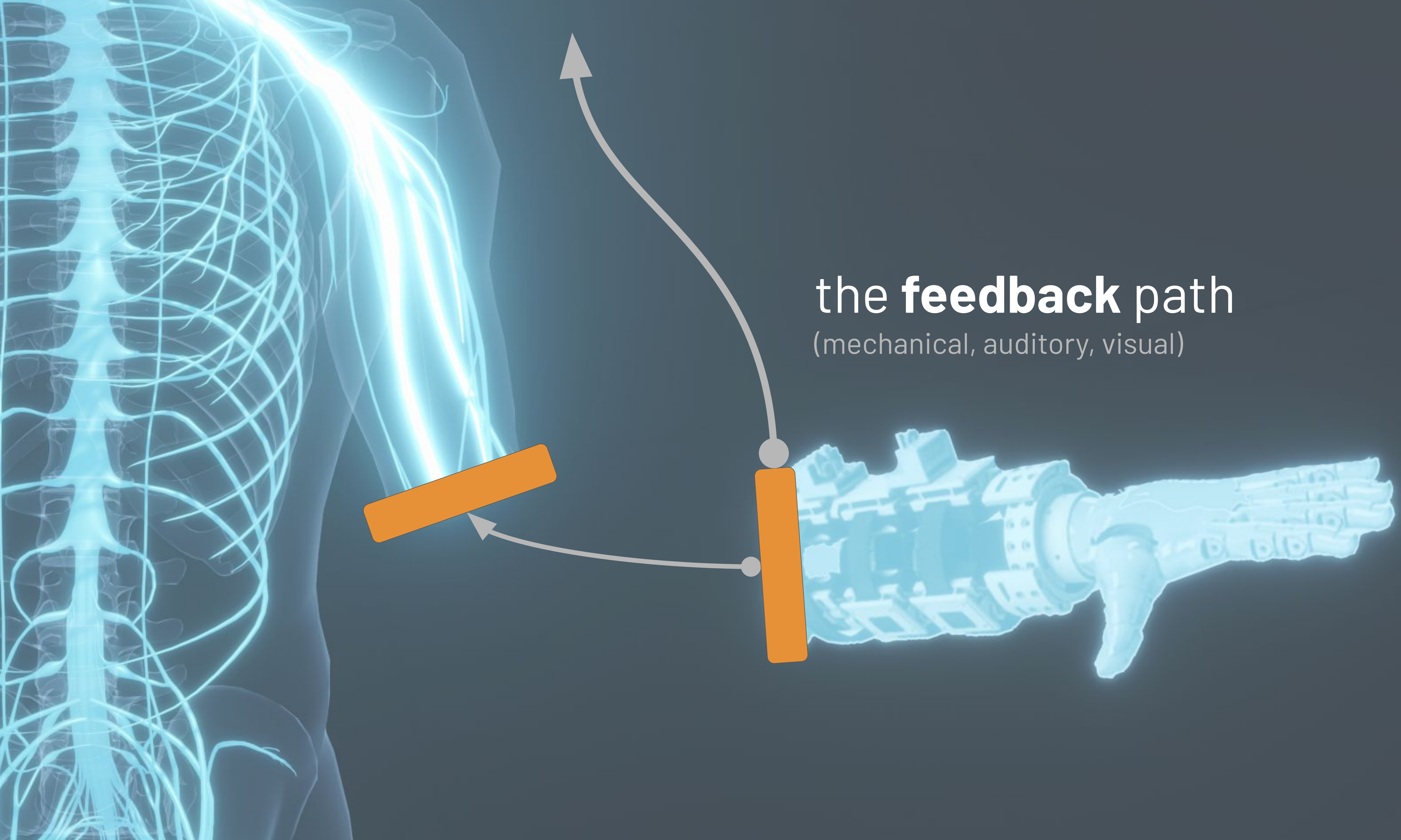
the **control** pathway

Hallworth, et al.,
MEC, 2020



machine intelligence

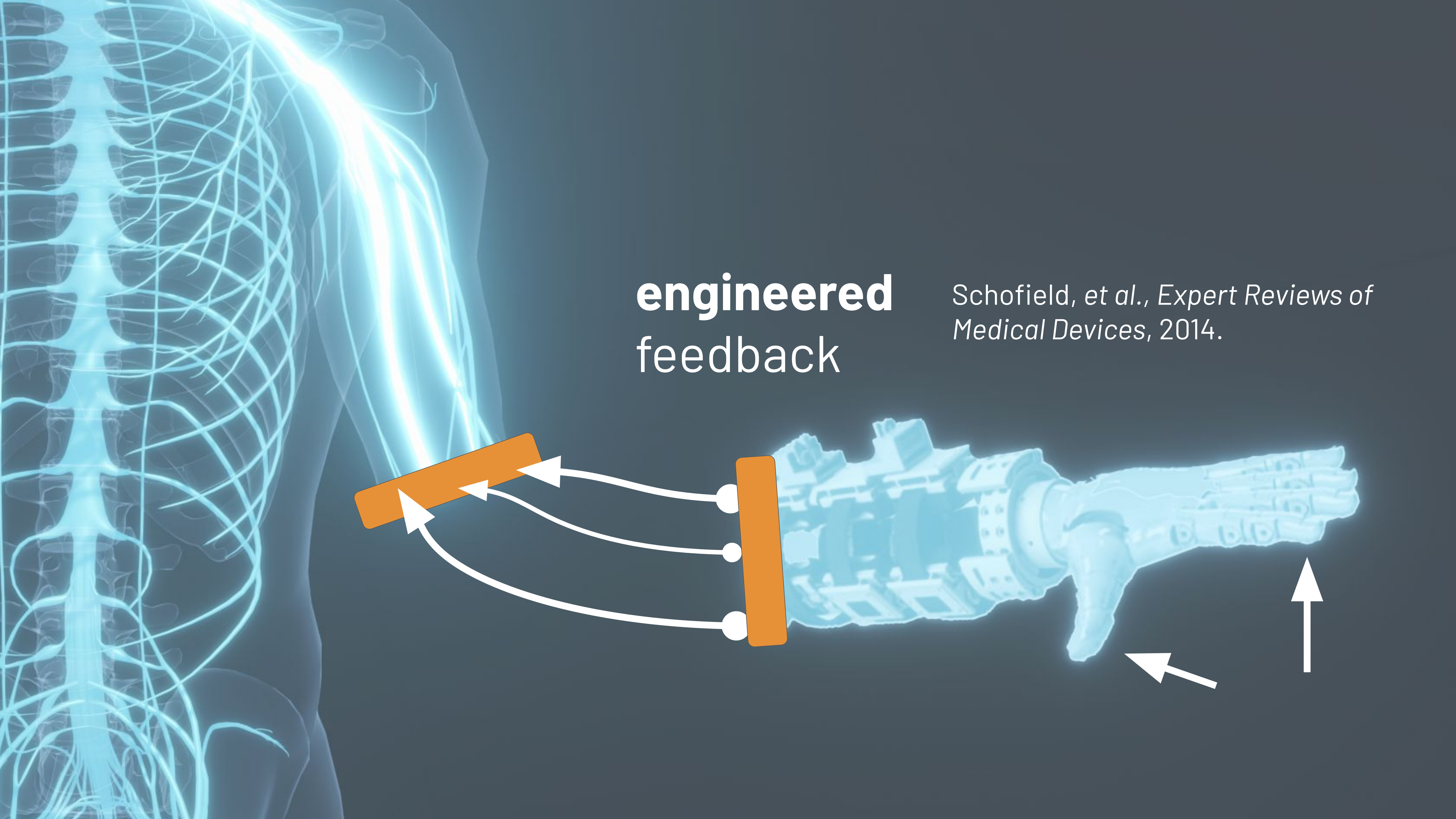
Shehata, et al.,
IEEE Sig. Proc. Magazine, 2021



the **feedback** path
(mechanical, auditory, visual)

**engineered
feedback**

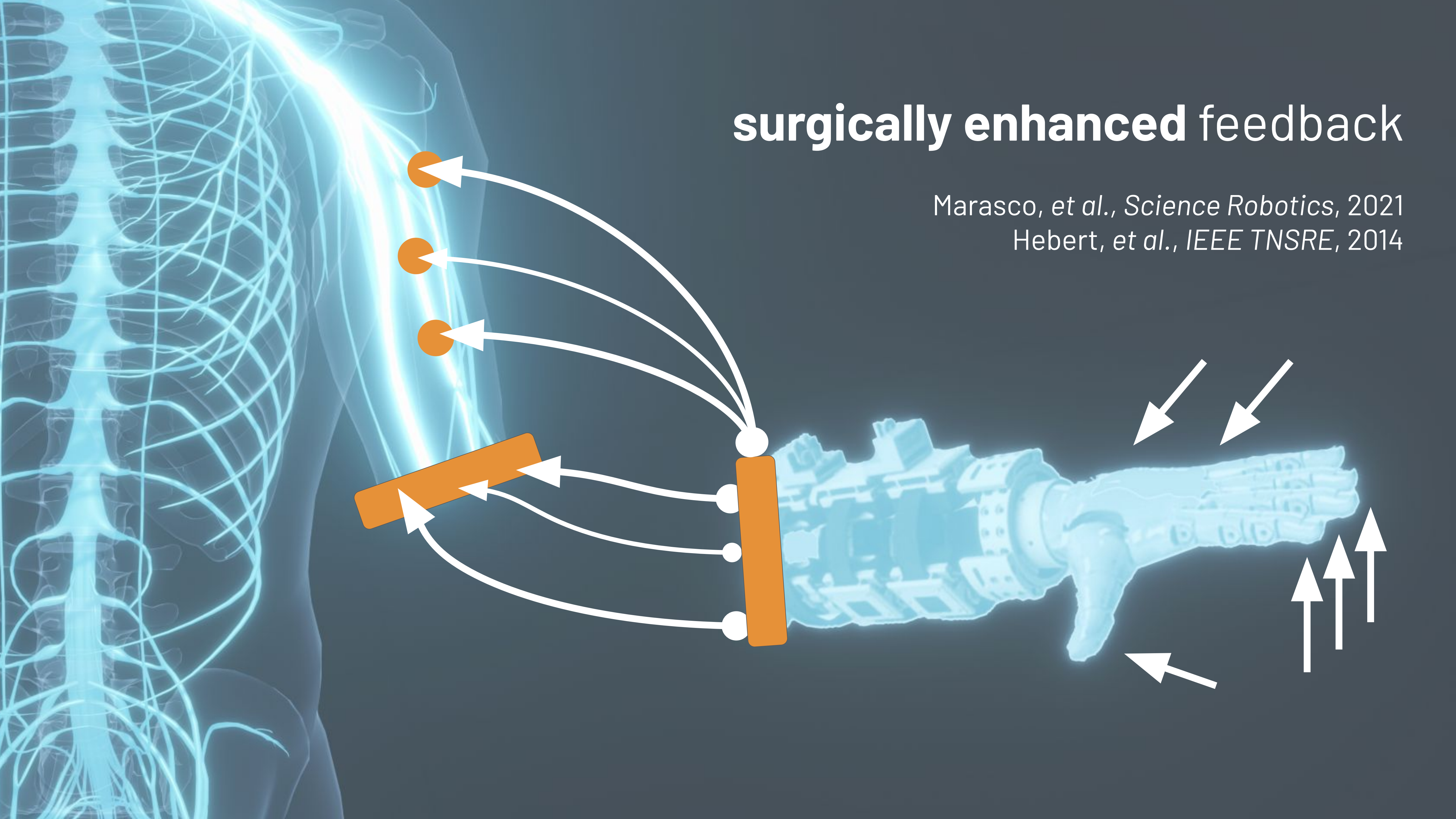
*Schofield, et al., Expert Reviews of
Medical Devices, 2014.*

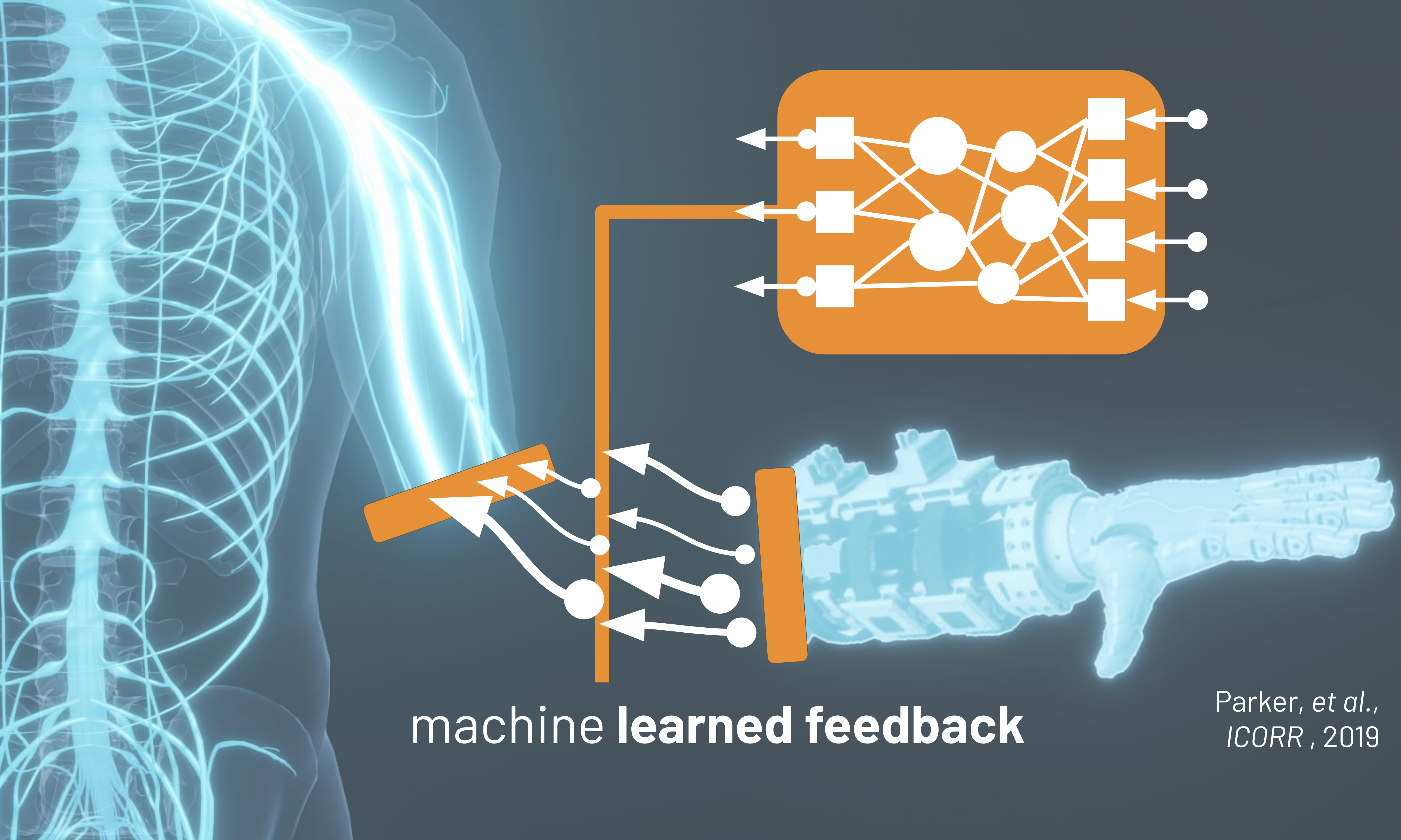


surgically enhanced feedback

Marasco, et al., *Science Robotics*, 2021

Hebert, et al., *IEEE TNSRE*, 2014





machine **learned feedback**

Parker, et al.,
ICORR, 2019

Expert-**Designed**
or Fixed Signalling

Emergent or Fully
Learned Signalling



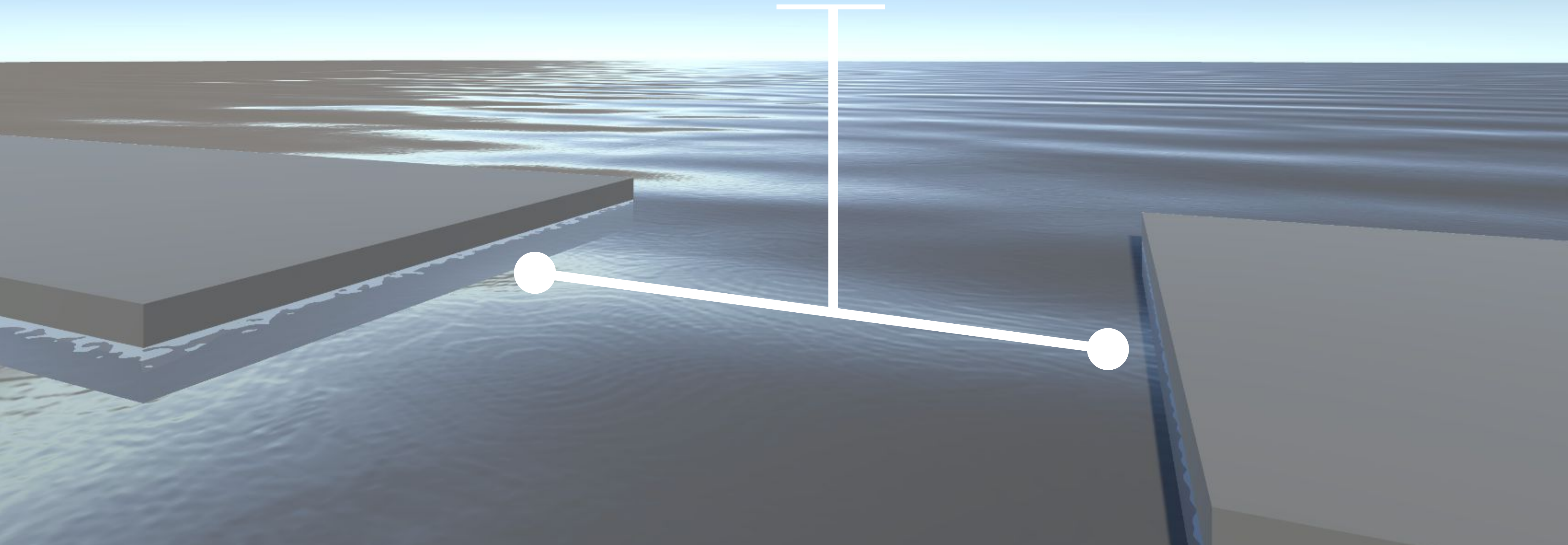
Crandall, et al.,
Nature Communications,
9:233, 2018.

Lazaridou and Baroni,
arXiv 2006.02419, 2020.

Jaques, et al., *ICML*, 2019.

Expert-**Designed**
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Expert-**Designed**
or Fixed Signalling

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a first, natural
stepping stone

Pavlovian signalling

Butcher *et al.*, 2022; Brenneis *et al.*,
2022; Pilarski *et al.*, 2022.

Pavlovian signalling is a process wherein learned, temporally extended predictions

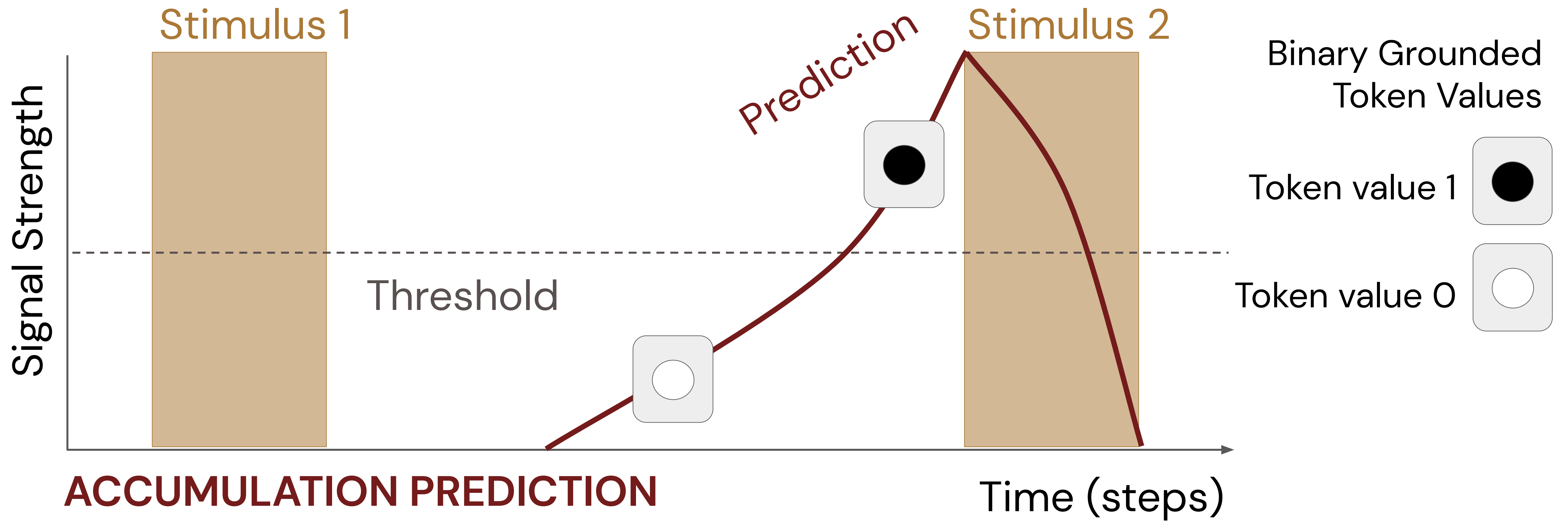
Butcher *et al.*, 2022; Brenneis *et al.*,
2022; Pilarski *et al.*, 2022.

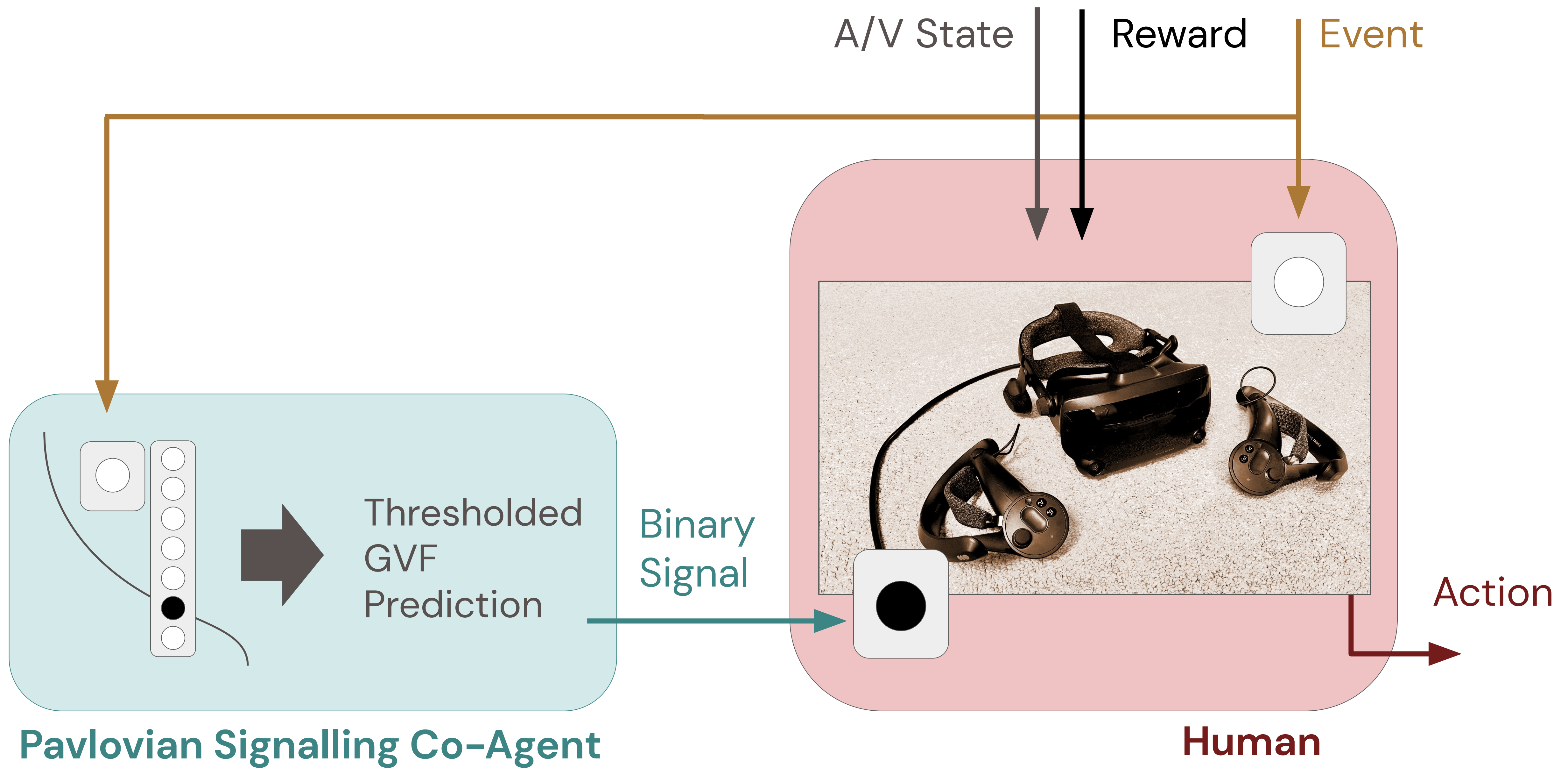
Pavlovian signalling is a process wherein learned, temporally extended predictions are mapped in a defined way to signals intended for receipt by a decision-making agent

Butcher *et al.*, 2022; Brenneis *et al.*, 2022; Pilarski *et al.*, 2022.

Pavlovian signalling is a process wherein learned, temporally extended predictions are mapped in a defined way to signals intended for receipt by a decision-making agent, and where these signals are grounded for the sender in the definition of the predictive question and mapping approach that generated them.

Butcher et al., 2022; Brenneis et al., 2022; Pilarski et al., 2022.





Butcher *et al.*, 2022; Brenneis *et al.*, 2022; Pilarski *et al.*, 2022.

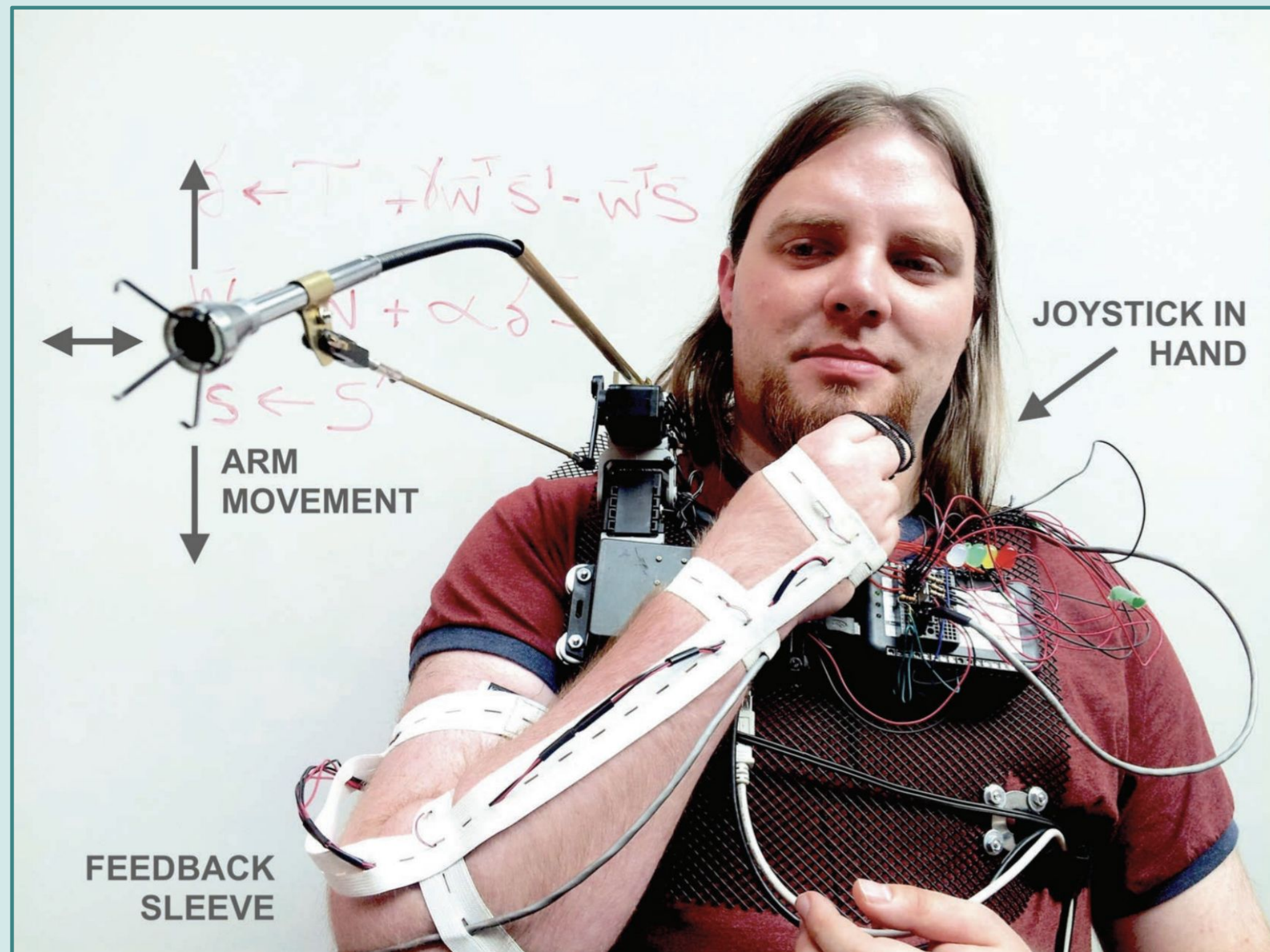
A virtual reality scene of a snowy forest. The ground is covered in a thick layer of snow. In the foreground, a person's hands are raised in a gesture of waiting or anticipation. The background shows snow-covered trees and bushes. The text "Waiting for wind to pass..." is overlaid on the top left of the image.

Waiting for wind to pass...

The Frost Hollow Experiments

Brenneis, *et al.*, "**Assessing human interaction in virtual reality with continually learning prediction agents** based on reinforcement learning algorithms: A pilot study," *Adaptive and Learning Agents (ALA) Workshop, AAMAS 2022*.

Pavlovian signalling in **motor prediction**.
Parker et al., *IEEE SMC* 2022 (submitted);
Parker et al., *ICORR* 2019.



Switching-based **exoskeleton control**.
Faridi et al., *ICORR* 2022.

Pavlovian signalling in **mode switching**.
Edwards et al., *BioRob* 2016.

Emergent communication during navigation.
Kalinowska et al., *CogSci* 2022;
Kalinowska et al., *ICLR EmeCom* 2022.

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Predicted muscle fatigue in
wheelchair propulsion. Pilarski, *et al.*,
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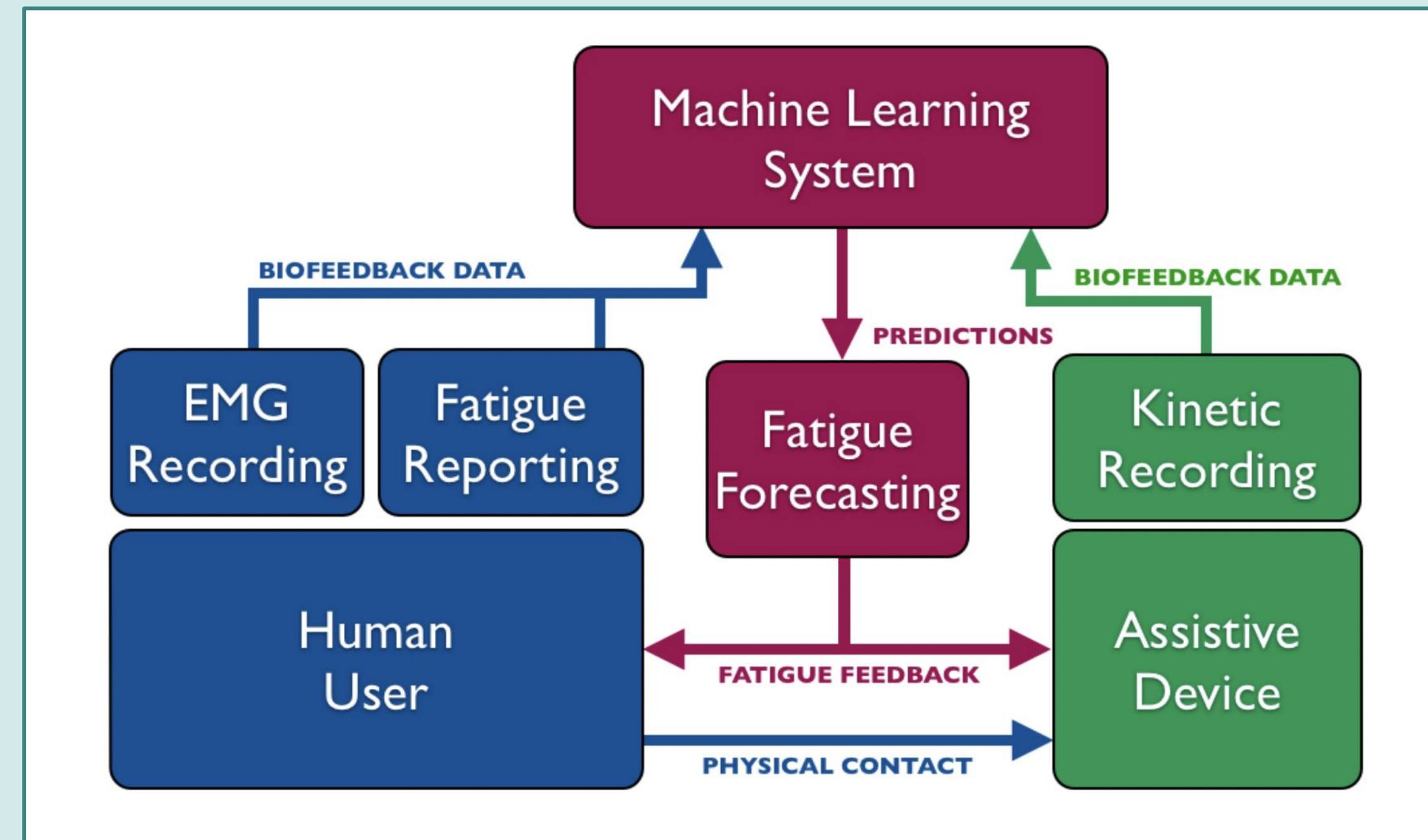
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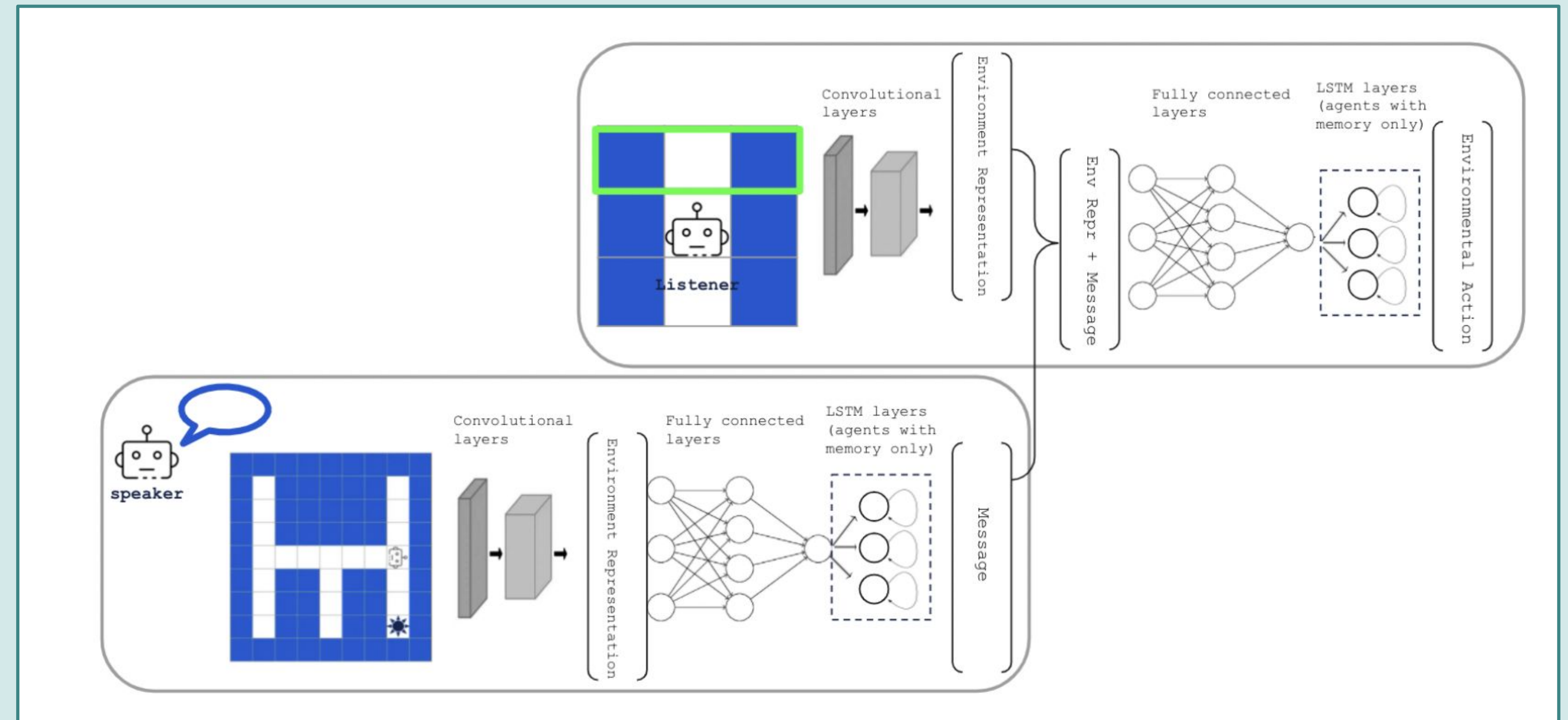
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Faridi et al., *ICORR* 2022.

Emergent communication during navigation.
Kalinowska et al., *CogSci* 2022;
Kalinowska et al., *ICLR EmeCom* 2022.

Context

Williams *et al.*, "Recurrent Convolutional Neural Networks as an Approach to **Position-Aware Myoelectric Prosthesis Control**," *IEEE TBME*, 2022.

Video courtesy:
Amii / Chris Onciul

Interpretation

Dawson *et al.*, "**Joint Action** is a Framework for Understanding Partnerships Between Humans and Upper Limb Prostheses," in preparation, 2022.

Mathewson *et al.*, "**Communicative Capital**: A Framework for Human-Machine Shared Agency and Collaborative Capacity," *Neural Computing and Applications*, 2022 (submitted); also "Communicative Capital for Prosthetic Agents," arXiv:1711.03676 [cs.AI].



Courtesy: The Canadian Press /
Amber Bracken

Assessment

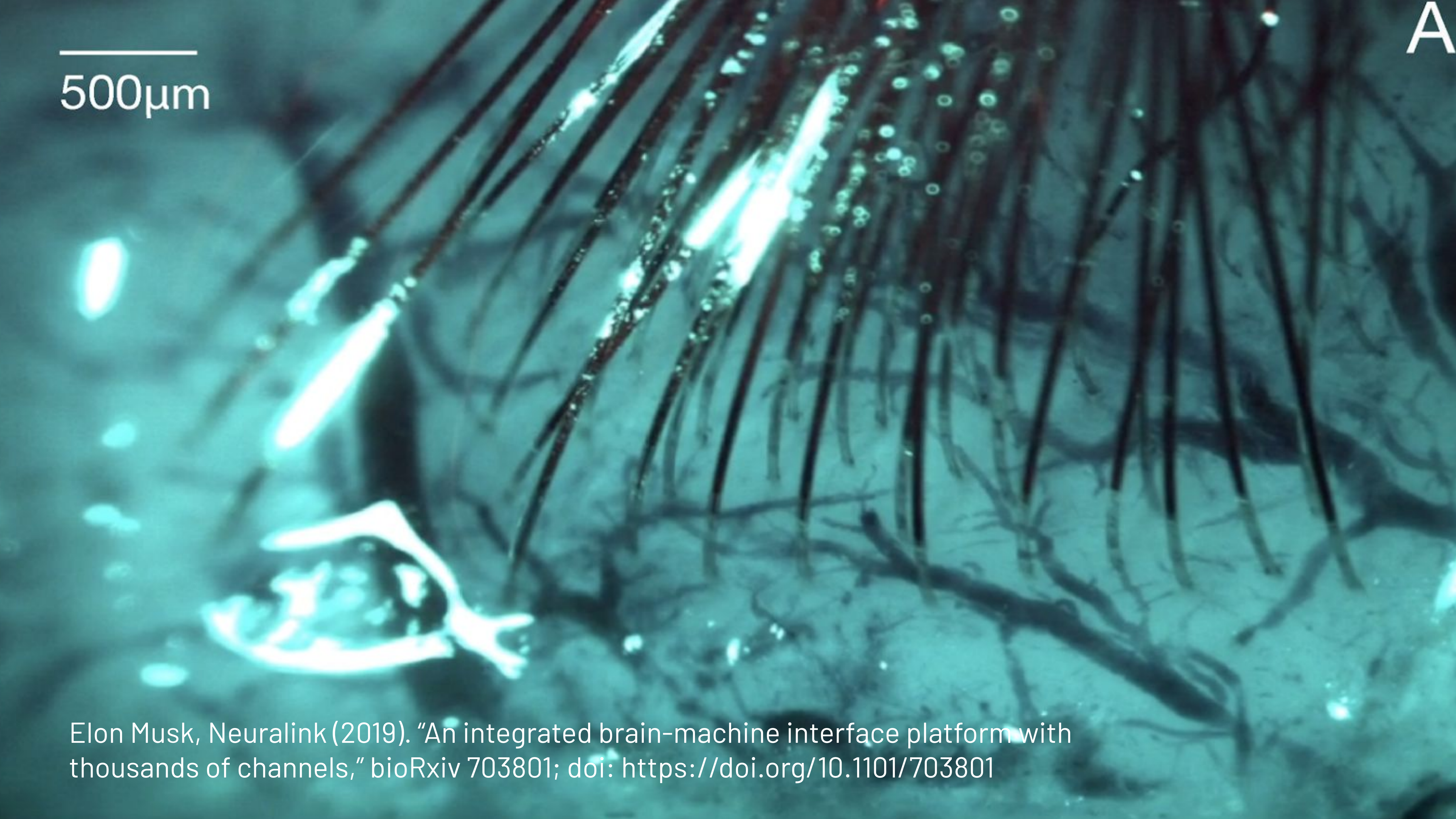
H. E. Williams, C. S. Chapman,
P. M. Pilarski, A. H. Vette, J. S.
Hebert, "**Gaze and Movement
Assessment (GaMA):**
Inter-site Validation of a
Visuomotor Upper Limb
Functional Protocol," *PLoS
One*, 14(12), e0219333, 2019.

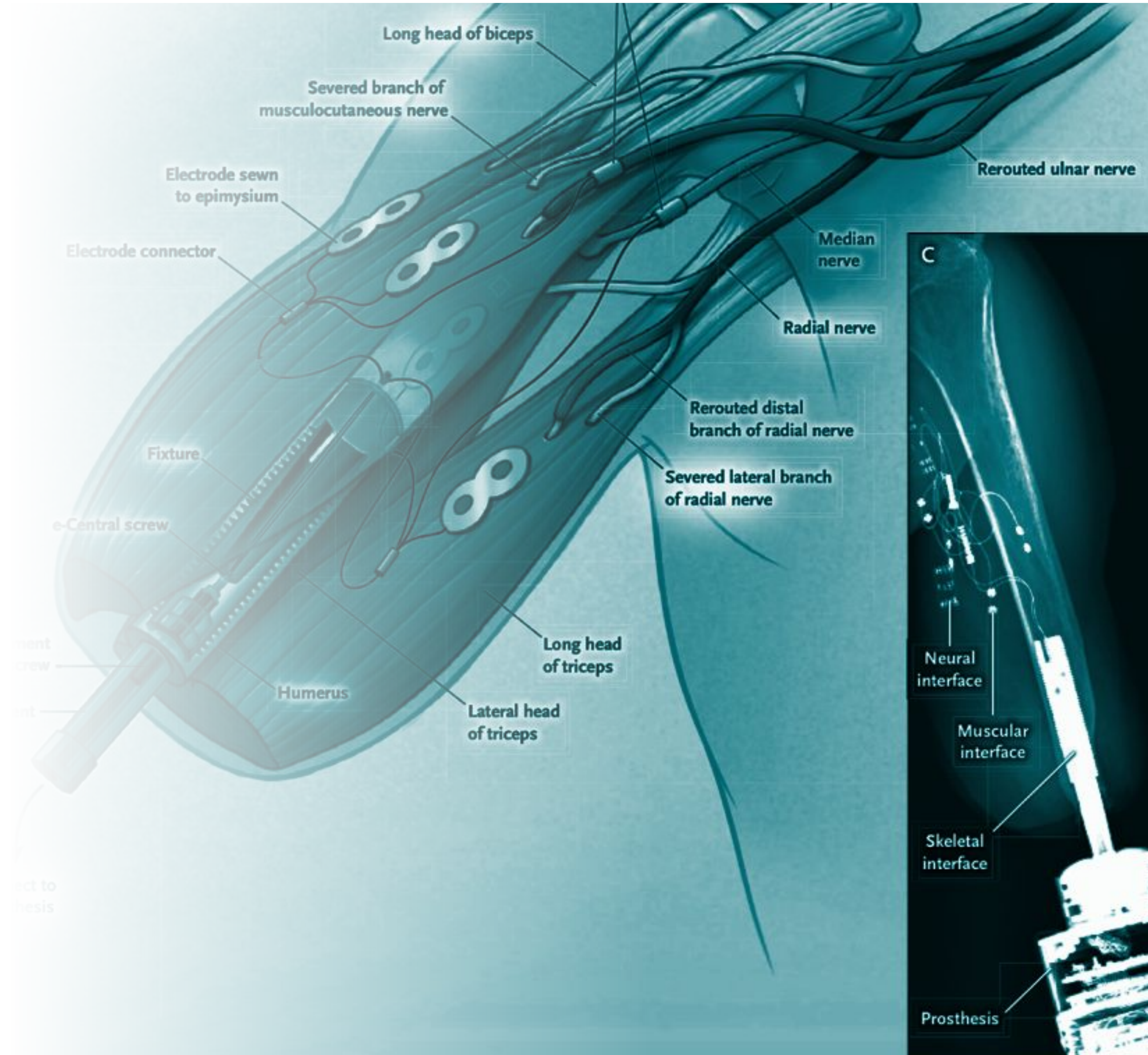
Video courtesy:
Amii / Chris Onciul

500μm

A

Elon Musk, Neuralink (2019). "An integrated brain-machine interface platform with thousands of channels," bioRxiv 703801; doi: <https://doi.org/10.1101/703801>



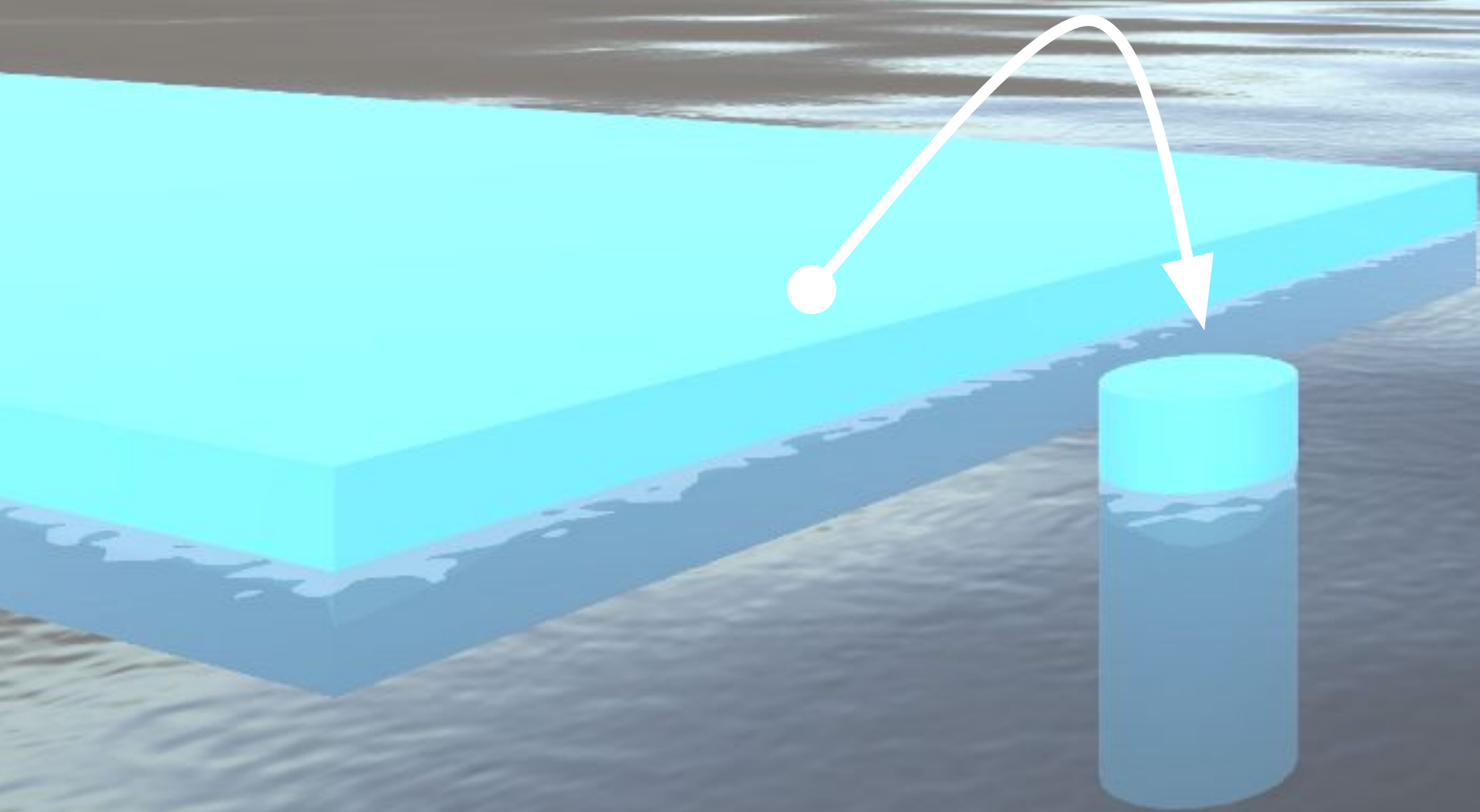


Ortiz-Catalan et al., *N Engl J Med* 2020; 382:1732-8.

Pavlovian signalling

Expert-**Designed**
or Fixed Signalling

Emergent or Fully
Learned Signalling



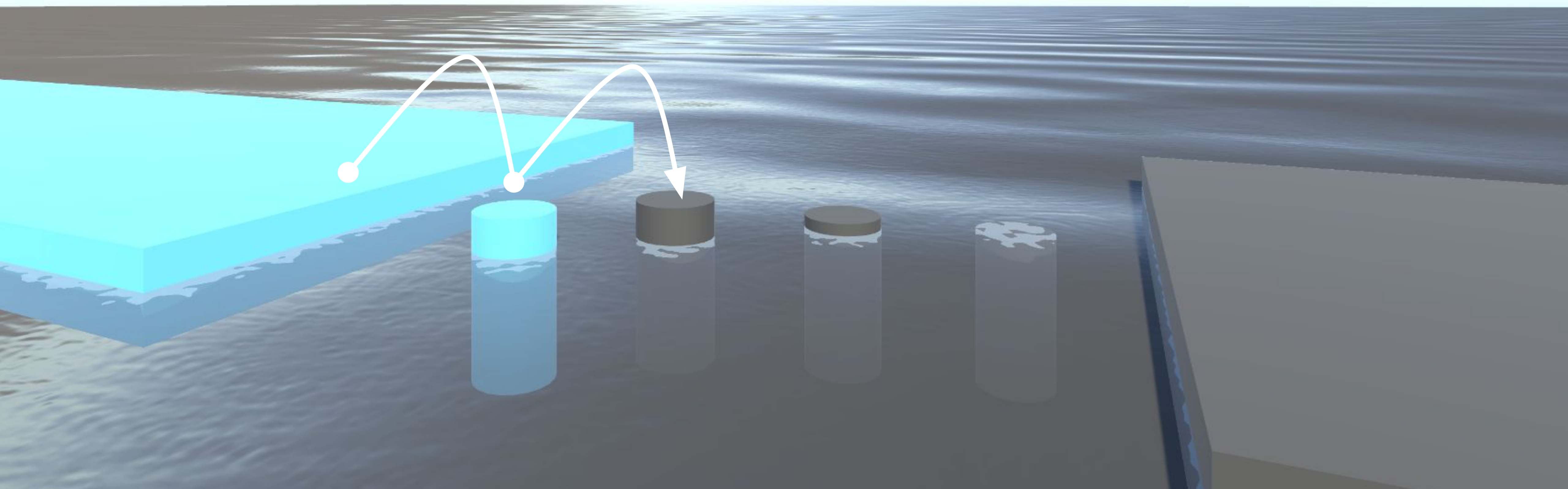
Pavlovian signalling
context

frameworks

assessment

Expert-**Designed**
or Fixed Signalling

Emergent or Fully
Learned Signalling



Pavlovian signalling

context

frameworks

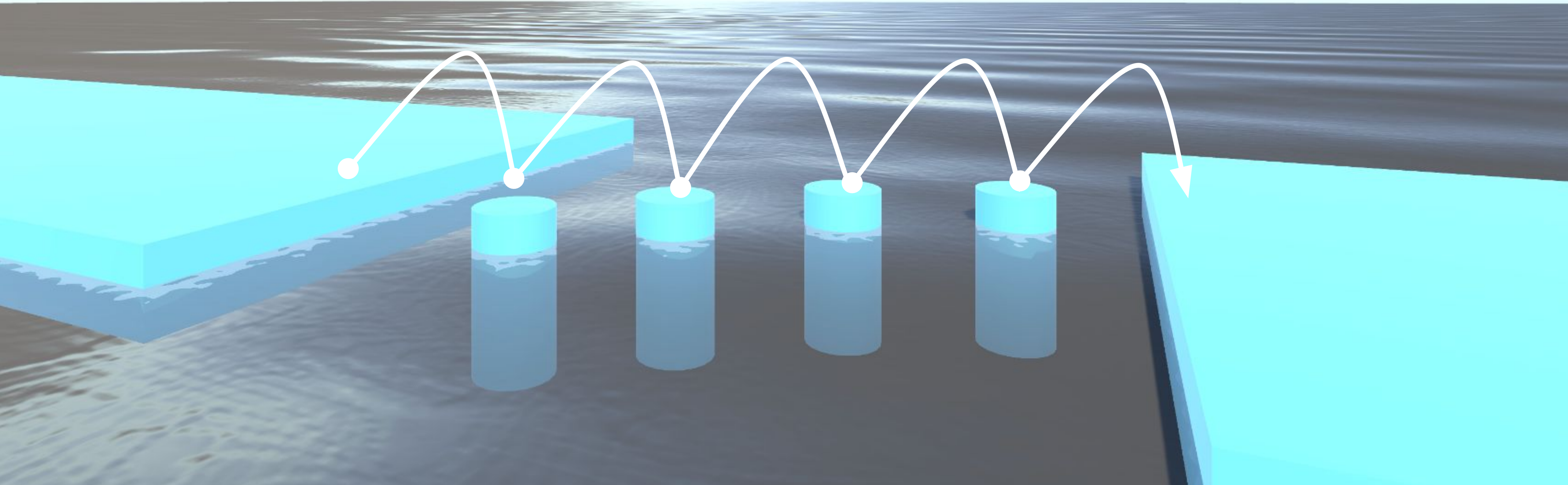
Expert-**Designed**
or Fixed Signalling

assessment

model learning

Emergent or Fully
Learned Signalling

policy learning



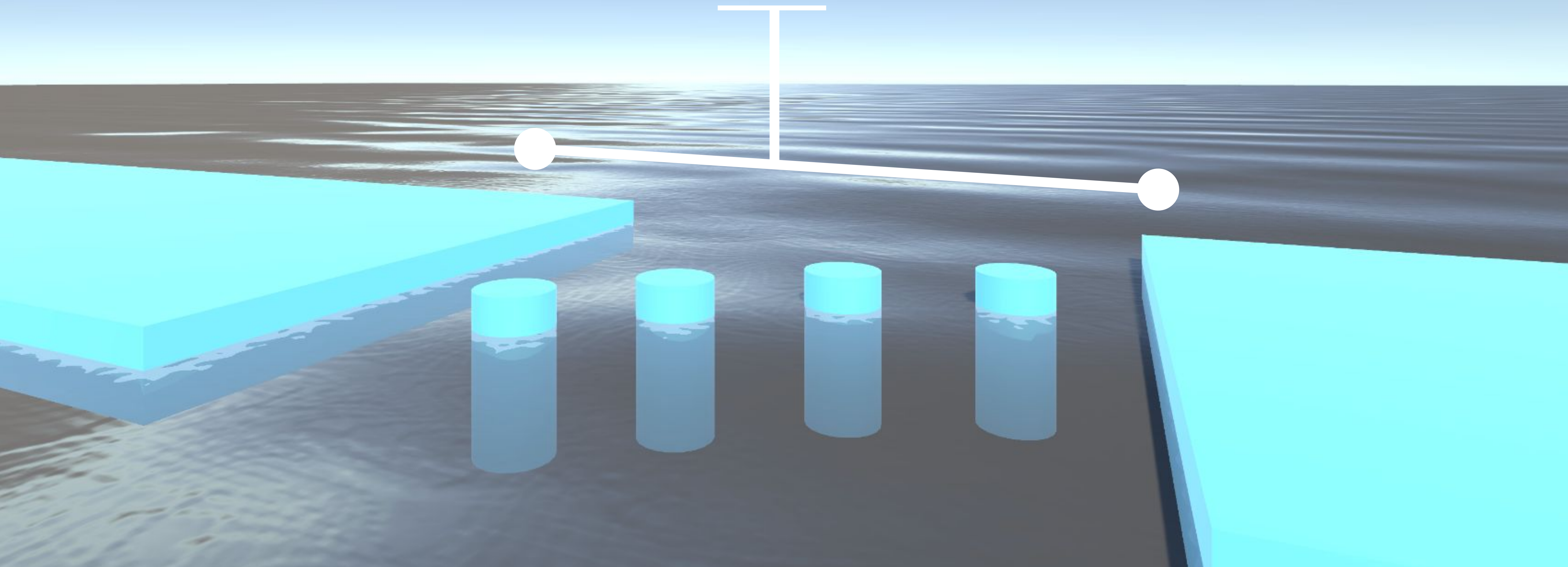
Ostensive-inferential Communication

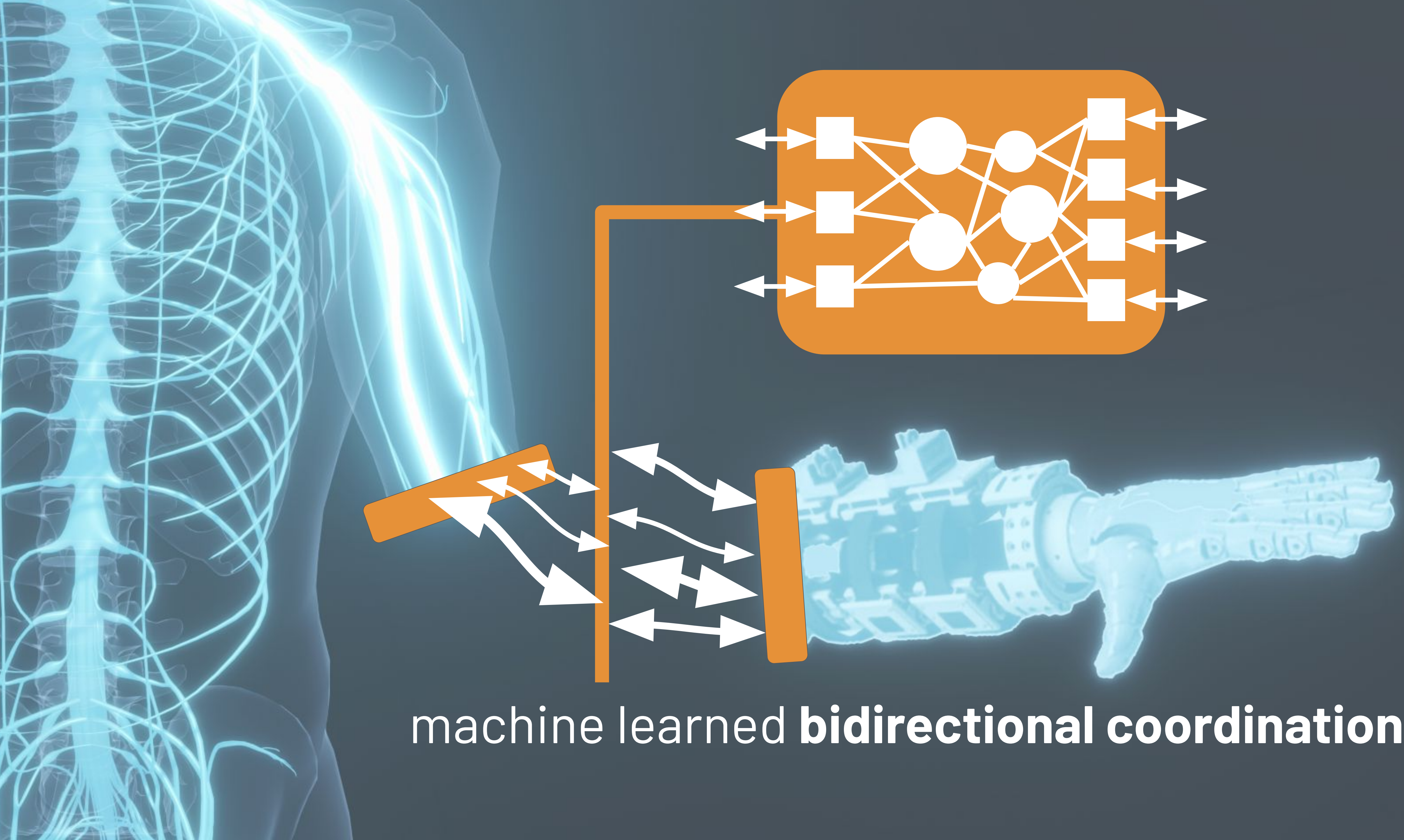
Scott-Phillips, *Speaking our Minds*, 2014.

Expert-**Designed**
or Fixed Signalling

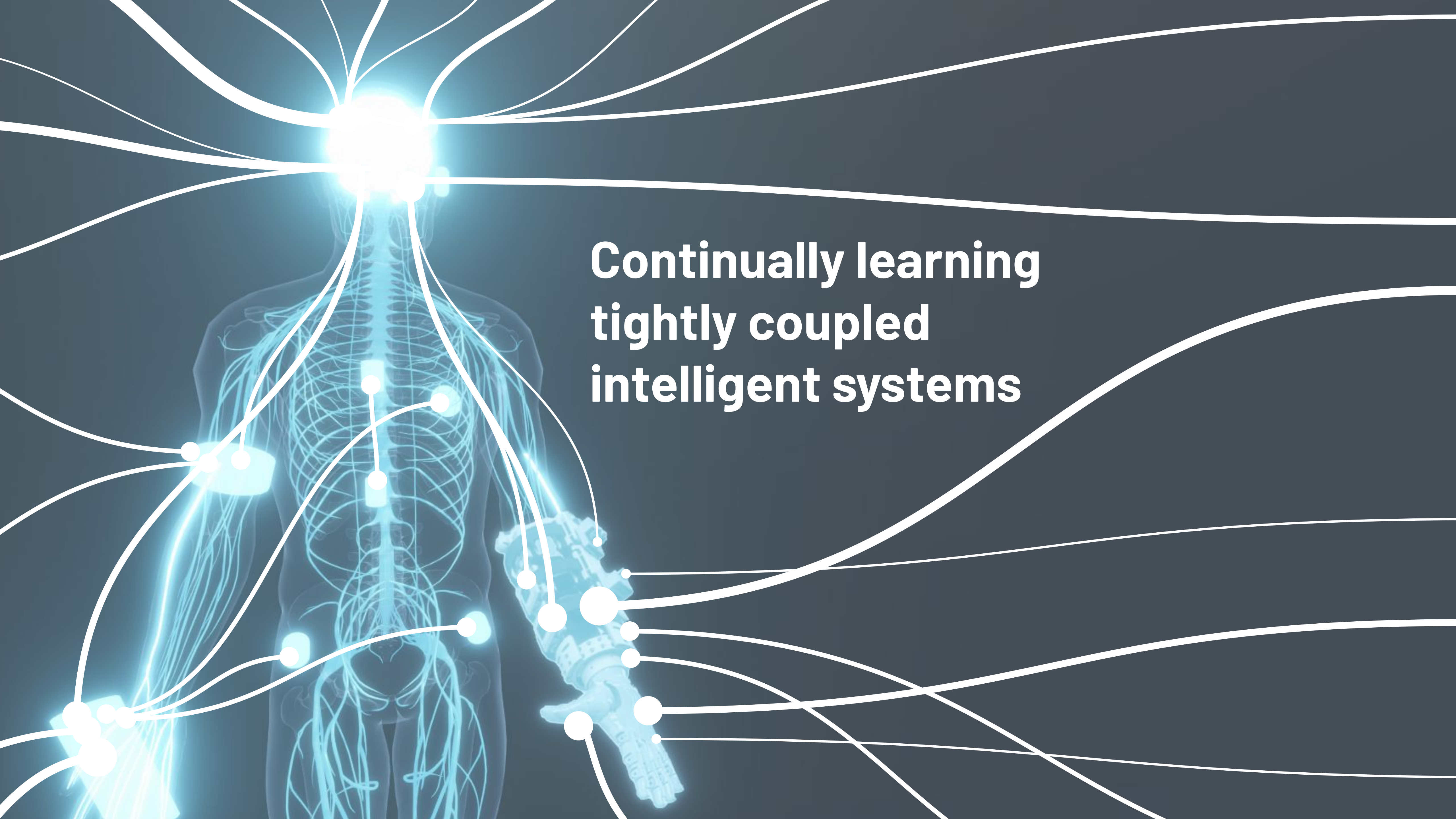
Joint Action
Sebanz, *et al.*, 2006.

Emergent or Fully
Learned Signalling





machine learned **bidirectional coordination**

The image features a central human silhouette rendered in a glowing blue, wireframe-like style. The figure's head is a bright, multi-pointed light source from which numerous white lines radiate outwards, some curving across the top of the frame. The torso and limbs are also connected to a network of glowing blue nodes and lines. On the right side, the human's right hand is replaced by a detailed, glowing blue robotic hand with visible joints and sensors. The background is a dark, gradient blue, and the overall aesthetic is futuristic and technological.

**Continually learning
tightly coupled
intelligent systems**



Post-surgery Osseointegration
Rehabilitation conducted at the
Glenrose Rehabilitation Hospital

Thank you and questions!

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K. Ming Chan
Erik Scheme
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Kory Mathewson
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Andrew Bolt
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Heather Williams
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Roshan Shariff
Nathan Wispinski
Ben Hallworth

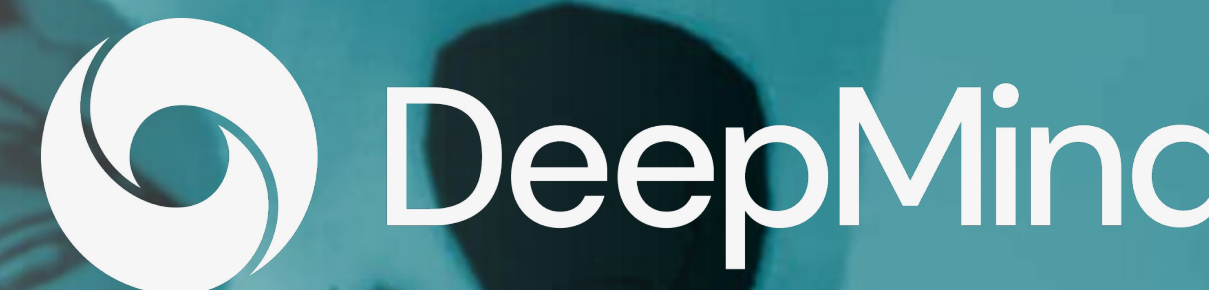
... and all the other members of our teams
and labs advising or contributing to aspects
the presented work.

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Government of Alberta.



SMART
NETWORK

Sensory
Motor
Adaptive
Rehabilitation
Technology



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